

Product data sheet

Specifications



Variable speed drive, Altivar Process ATV900, ATV930, 1,5 kW, 400/480 V, with braking unit, IP21

ATV930U15N4

Main

Range of product	Altivar Process ATV900
Device application	Industrial application
Product or component type	Variable speed drive
Product destination	Asynchronous motors Synchronous motors
Product specific application	Process for industrial
Variant	With braking chopper Standard version
Network number of phases	3 phases
Mounting mode	Wall mount
Communication port protocol	Modbus TCP EtherNet/IP Modbus serial
[Us] rated supply voltage	380...480 V - 15...10 %
Motor power kW	1.5 kW for normal duty 0.75 kW for heavy duty
Motor power hp	2.0 hp for normal duty 1.0 hp for heavy duty
Continuous output current	4 A at 4 kHz for normal duty 2.2 A at 4 kHz for heavy duty
EMC filter	Integrated With EMC plate option
IP degree of protection	IP21
Degree of protection	UL type 1
Option module	Slot A: communication module for Profibus DP V1 Slot A: communication module for PROFINET Slot A: communication module for DeviceNet Slot A: communication module for EtherCAT Slot A: communication module for CANopen daisy chain RJ45 Slot A: communication module for CANopen SUB-D 9 Slot A: communication module for CANopen screw terminals Slot A/slot B/slot C: digital and analog I/O extension module Slot A/slot B/slot C: output relay extension module Slot B: 5/12 V digital encoder interface module Slot B: analog encoder interface module Slot B: resolver encoder interface module communication module for Ethernet Powerlink
Discrete input logic	16 preset speeds
Asynchronous motor control profile	Constant torque standard Optimized torque mode Variable torque standard

Synchronous motor control profile	Permanent magnet motor Synchronous reluctance motor
Maximum output frequency	599 Hz
Switching frequency	2...16 kHz adjustable 4...16 kHz with derating factor
Nominal switching frequency	4 kHz
Line current	3.0 A at 380 V (normal duty) 1.7 A at 380 V (heavy duty) 2.6 A at 480 V (normal duty) 1.5 A at 480 V (heavy duty)
Apparent power	2.2 kVA at 480 V (normal duty) 1.2 kVA at 480 V (heavy duty)
Maximum transient current	4.8 A during 60 s (normal duty) 3.3 A during 60 s (heavy duty)
Network frequency	50...60 Hz
Prospective line Isc	50 kA
Complementary	
Discrete input number	10
Discrete input type	DI1...DI8 programmable, 24 V DC (≤ 30 V), impedance: 3.5 kOhm DI7, DI8 programmable as pulse input: 0...30 kHz, 24 V DC (≤ 30 V) STOA, STOB safe torque off, 24 V DC (≤ 30 V), impedance: > 2.2 kOhm
Discrete output number	2
Discrete output type	Logic output DQ+ 0...1 kHz ≤ 30 V DC 100 mA Programmable as pulse output DQ+ 0...30 kHz ≤ 30 V DC 20 mA Logic output DQ- 0...1 kHz ≤ 30 V DC 100 mA
Analogue input number	3
Analogue input type	AI1, AI2, AI3 software-configurable voltage: 0...10 V DC, impedance: 30 kOhm, resolution 12 bits AI1, AI2, AI3 software-configurable current: 0...20 mA/4...20 mA, impedance: 250 Ohm, resolution 12 bits
Analogue output number	2
Analogue output type	Software-configurable voltage AQ1, AQ2: 0...10 V DC impedance 470 Ohm, resolution 10 bits Software-configurable current AQ1, AQ2: 0...20 mA impedance 500 Ohm, resolution 10 bits
Relay output number	3
Relay output type	Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles Configurable relay logic R2: sequence relay NO electrical durability 1000000 cycles Configurable relay logic R3: sequence relay NO electrical durability 1000000 cycles
Maximum switching current	Relay output R1 on resistive load, $\cos \phi = 1$: 3 A at 250 V AC Relay output R1 on resistive load, $\cos \phi = 1$: 3 A at 30 V DC Relay output R1 on inductive load, $\cos \phi = 0.4$ and $L/R = 7$ ms: 2 A at 250 V AC Relay output R1 on inductive load, $\cos \phi = 0.4$ and $L/R = 7$ ms: 2 A at 30 V DC Relay output R2, R3 on resistive load, $\cos \phi = 1$: 5 A at 250 V AC Relay output R2, R3 on resistive load, $\cos \phi = 1$: 5 A at 30 V DC Relay output R2, R3 on inductive load, $\cos \phi = 0.4$ and $L/R = 7$ ms: 2 A at 250 V AC Relay output R2, R3 on inductive load, $\cos \phi = 0.4$ and $L/R = 7$ ms: 2 A at 30 V DC
Minimum switching current	Relay output R1, R2, R3: 5 mA at 24 V DC
Physical interface	Ethernet 2-wire RS 485
Connector type	2 RJ45 1 RJ45
Method of access	Slave Modbus TCP
Transmission rate	10, 100 Mbits 4.8 kbps 9600 bit/s 19200 bit/s
Transmission frame	RTU
Number of addresses	1...247
Data format	8 bits, configurable odd, even or no parity
Type of polarization	No impedance

4 quadrant operation possible	True
Acceleration and deceleration ramps	Linear adjustable separately from 0.01...9999 s
Motor slip compensation	Adjustable Can be suppressed Automatic whatever the load Not available in permanent magnet motor law
Braking to standstill	By DC injection
Brake chopper integrated	True
Maximum input current	3.0 A
Maximum output voltage	480.0 V
Relative symmetric network frequency tolerance	5 %
Base load current at high overload	2.2 A
Base load current at low overload	4.0 A
Power dissipation in W	Natural convection: 28 W at 380 V, switching frequency 4 kHz Forced convection: 41 W at 380 V, switching frequency 4 kHz
With safety function Safely Limited Speed (SLS)	True
With safety function Safe brake management (SBC/SBT)	True
With safety function Safe Operating Stop (SOS)	False
With safety function Safe Position (SP)	False
With safety function Safe programmable logic	False
With safety function Safe Speed Monitor (SSM)	False
With safety function Safe Stop 1 (SS1)	True
With sft fct Safe Stop 2 (SS2)	False
With safety function Safe torque off (STO)	True
With safety function Safely Limited Position (SLP)	False
With safety function Safe Direction (SDI)	False
Protection type	Thermal protection: motor Safe torque off: motor Motor phase break: motor Thermal protection: drive Safe torque off: drive Overheating: drive Overcurrent between output phases and earth: drive Overload of output voltage: drive Short-circuit protection: drive Motor phase break: drive Overvoltages on the DC bus: drive Line supply overvoltage: drive Line supply undervoltage: drive Line supply phase loss: drive Overspeed: drive Break on the control circuit: drive
Quantity per set	1
Width	144 mm
Height	350 mm
Depth	206 mm

Net weight	4.5 kg
Electrical connection	Control: screw terminal 0.5...1.5 mm²/AWG 20...AWG 16 Line side: screw terminal 2.5...6 mm²/AWG 14...AWG 10 Motor: screw terminal 2.5...6 mm²/AWG 14...AWG 10 DC bus: screw terminal 2.5...6 mm²/AWG 14...AWG 10 10/100 Mbit/s for Ethernet IP/Modbus TCP 4.8, 9.6, 19.2, 38.4 kbit/s for Modbus serial
Exchange mode	Half duplex, full duplex, autonegotiation Ethernet IP/Modbus TCP 8 bits, configurable odd, even or no parity for Modbus serial
Type of polarization	No impedance for Modbus serial 1...247 for Modbus serial
Supply	External supply for digital inputs: 24 V DC (19...30 V), <1.25 mA, protection type: overload and short-circuit protection Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10 mA, protection type: overload and short-circuit protection Internal supply for digital inputs and STO: 24 V DC (21...27 V), <200 mA, protection type: overload and short-circuit protection
Local signalling	Local diagnostic: 3 LED (mono/dual colour) Embedded communication status: 5 LED (dual colour) Communication module status: 2 LED (dual colour) Presence of voltage: 1 LED (red)
Input compatibility	DI1...DI8: discrete input level 1 PLC conforming to EN/IEC 61131-2 DI7, DI8: pulse input level 1 PLC conforming to IEC 65A-68 STOA, STOB: discrete input level 1 PLC conforming to EN/IEC 61131-2 Positive logic (source) (DI1...DI8), < 5 V (state 0), > 11 V (state 1) Negative logic (sink) (DI1...DI8), > 16 V (state 0), < 10 V (state 1) Positive logic (source) (DI7, DI8), < 0.6 V (state 0), > 2.5 V (state 1) Positive logic (source) (STOA, STOB), < 5 V (state 0), > 11 V (state 1)
Sampling duration	2 ms +/- 0.5 ms (DI1...DI8) - discrete input 5 ms +/- 1 ms (DI7, DI8) - pulse input 1 ms +/- 1 ms (AI1, AI2, AI3) - analog input 5 ms +/- 1 ms (AQ1, AQ2) - analog output
Accuracy	+/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input +/- 1 % AQ1, AQ2 for a temperature variation 60 °C analog output
Linearity error	AI1, AI2, AI3: +/- 0.15 % of maximum value for analog input AQ1, AQ2: +/- 0.2 % for analog output
Refresh time	Relay output (R1, R2, R3): 5 ms (+/- 0.5 ms)
Isolation	Between power and control terminals
Environment	
Operating altitude	<= 1000 m without derating 1000...4800 m with current derating 1 % per 100 m
Operating position	Vertical +/- 10 degree
Product certifications	TÜV CSA UL
Marking	CE
Standards	UL 508C EN/IEC 61800-3 EN/IEC 61800-5-1 IEC 61000-3-12 IEC 60721-3 IEC 61508 IEC 13849-1
Maximum THDI	<48 % full load conforming to IEC 61000-3-12
Assembly style	Enclosed
Electromagnetic compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6
Environmental class (during operation)	Class 3C3 according to IEC 60721-3-3 Class 3S3 according to IEC 60721-3-3

Maximum acceleration under shock impact (during operation)	150 m/s² at 11 ms
Maximum acceleration under vibrational stress (during operation)	10 m/s² at 13...200 Hz
Maximum deflection under vibratory load (during operation)	1.5 mm at 2...13 Hz
Permitted relative humidity (during operation)	Class 3K5 according to EN 60721-3
Volume of cooling air	38 m3/h
Overvoltage category	III
Regulation loop	Adjustable PID regulator
Insulation resistance	> 1 MOhm 500 V DC for 1 minute to earth
Noise level	54.5 dB conforming to 86/188/EEC
Vibration resistance	1.5 mm peak to peak (f= 2...13 Hz) conforming to IEC 60068-2-6 1 gn (f= 13...200 Hz) conforming to IEC 60068-2-6
Shock resistance	15 gn for 11 ms conforming to IEC 60068-2-27
Environmental characteristic	Chemical pollution resistance class 3C3 conforming to EN/IEC 60721-3-3 Dust pollution resistance class 3S3 conforming to EN/IEC 60721-3-3
Relative humidity	5...95 % without condensation conforming to IEC 60068-2-3
Ambient air temperature for operation	-15...50 °C (without derating) 50...60 °C (with derating factor)
Noise level	54.5 dB
Pollution degree	2
Ambient air transport temperature	-40...70 °C
Ambient air temperature for storage	-40...70 °C

Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	31 cm
Package 1 Width	19 cm
Package 1 Length	41 cm
Package 1 Weight	5.894 kg
Unit Type of Package 2	P06
Number of Units in Package 2	6
Package 2 Height	75 cm
Package 2 Width	60 cm
Package 2 Length	80 cm
Package 2 Weight	47.806 kg

Offer Sustainability

Sustainable offer status	Green Premium product
REACH Regulation	REACH Declaration
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope) EU RoHS Declaration

Mercury free	Yes
China RoHS Regulation	China RoHS declaration
RoHS exemption information	Yes
Environmental Disclosure	Product Environmental Profile
Circularity Profile	End of Life Information
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins
California proposition 65	WARNING: This product can expose you to chemicals including: Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm. For more information go to www.P65Warnings.ca.gov
Upgradeability	Upgraded components available

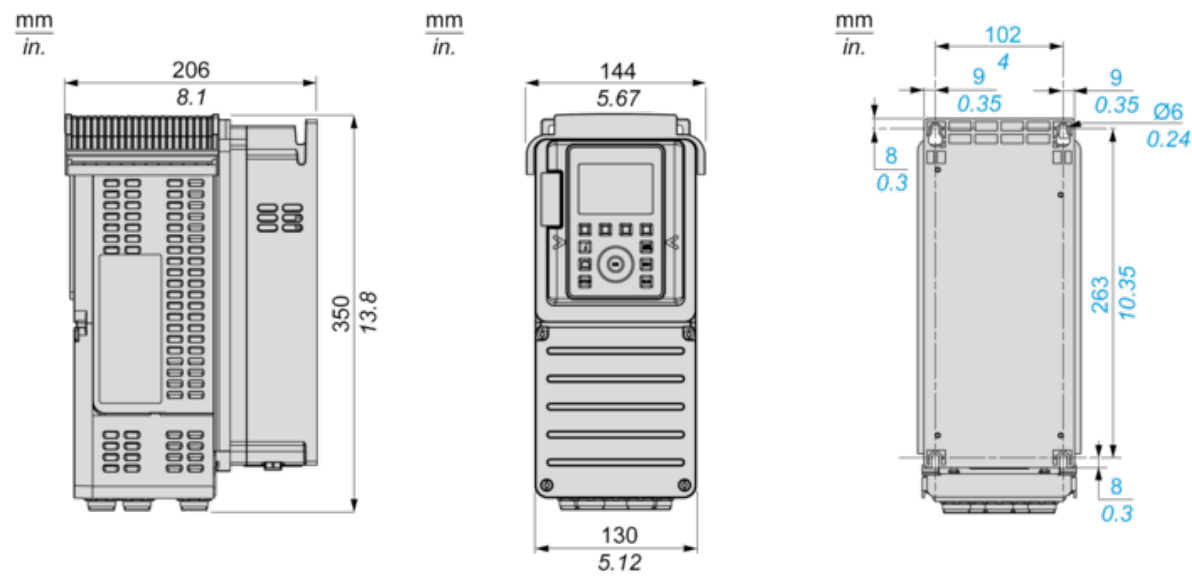
Product data sheet

Dimensions Drawings

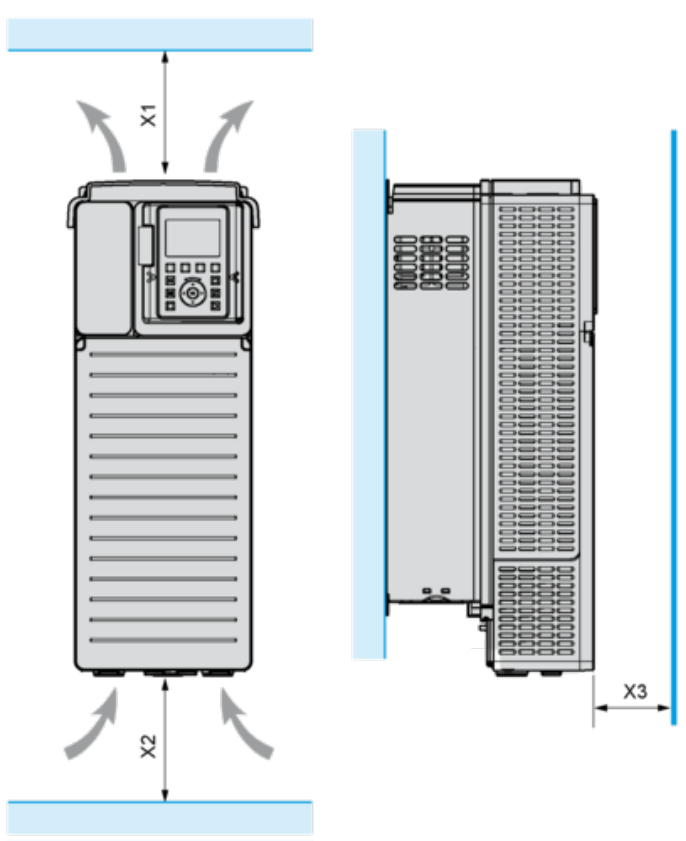
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Dimensions

Right, Front and Rear View



Clearances

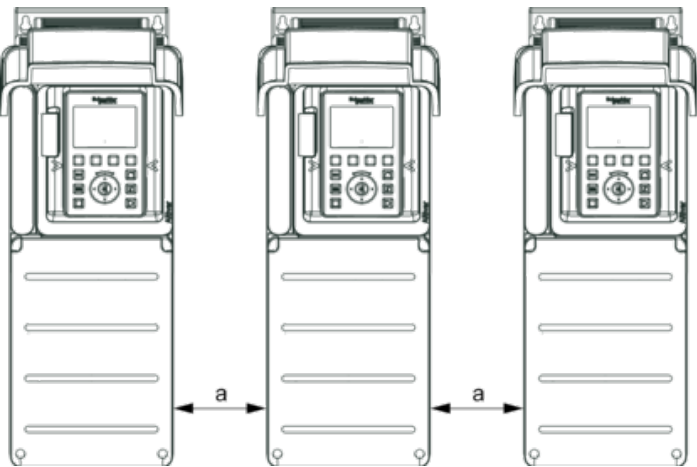


X1	X2	X3
≥ 100 mm (3.94 in.)	≥ 100 mm (3.94 in.)	≥ 10 mm (0.39 in.)

- Mount the device in a vertical position ($\pm 10^\circ$). This is required for cooling the device.
- Do not mount the device close to heat sources.
- Leave sufficient free space so that the air required for cooling purposes can circulate from the bottom to the top of the drive.

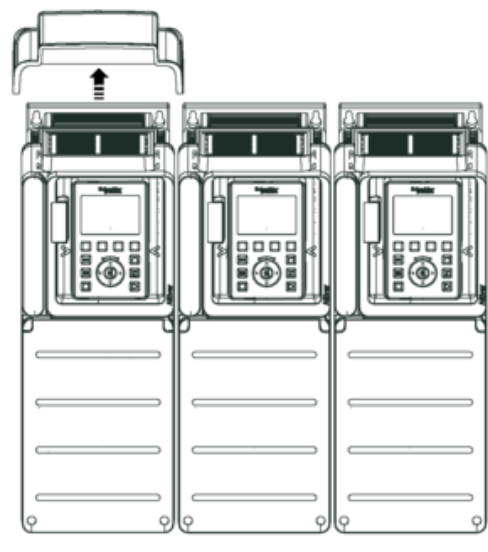
Mounting Types

Mounting Type A: Individual IP21

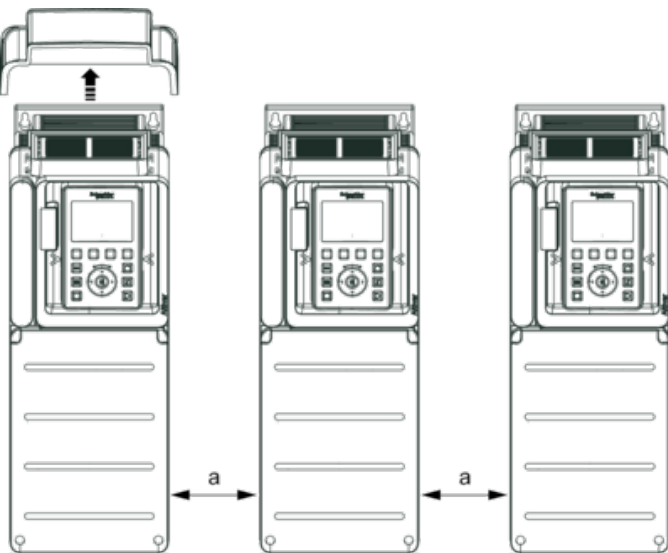


$a \geq 100\text{ mm (3.94 in.)}$

Mounting Type B: Side by Side IP20



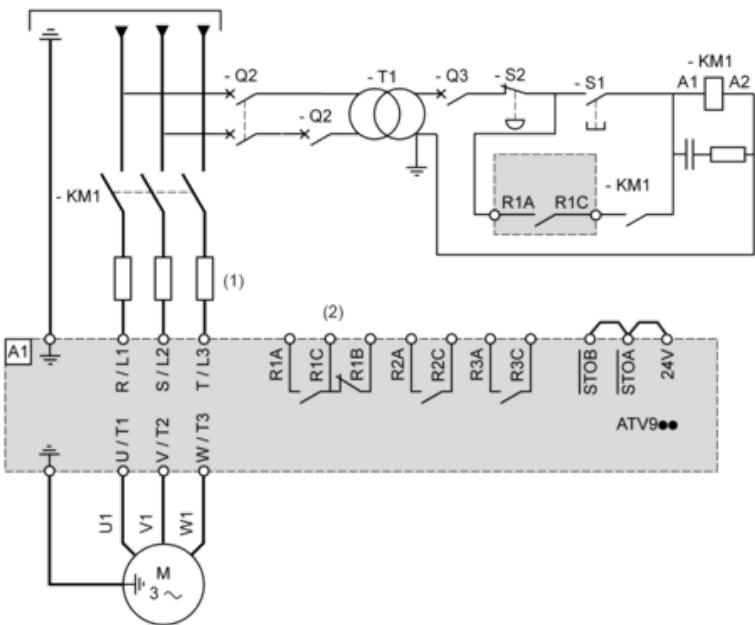
Mounting Type C: Individual IP20



$a \geq 0$

Three-Phase Power Supply with Upstream Breaking via Line Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



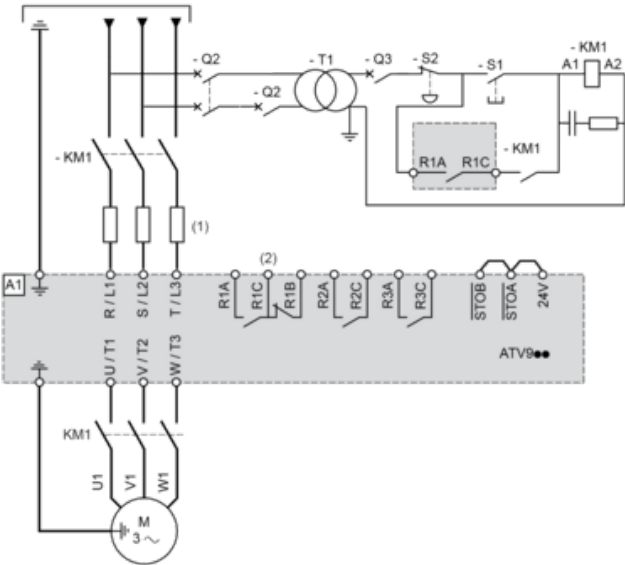
- (1) Line choke if used
 - (2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.
- A1 : Drive
KM1 : Line Contactor
Q2, Q3 : Circuit breakers
S1, S2 : Pushbuttons
T1 : Transformer for control part

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Connections and Schema

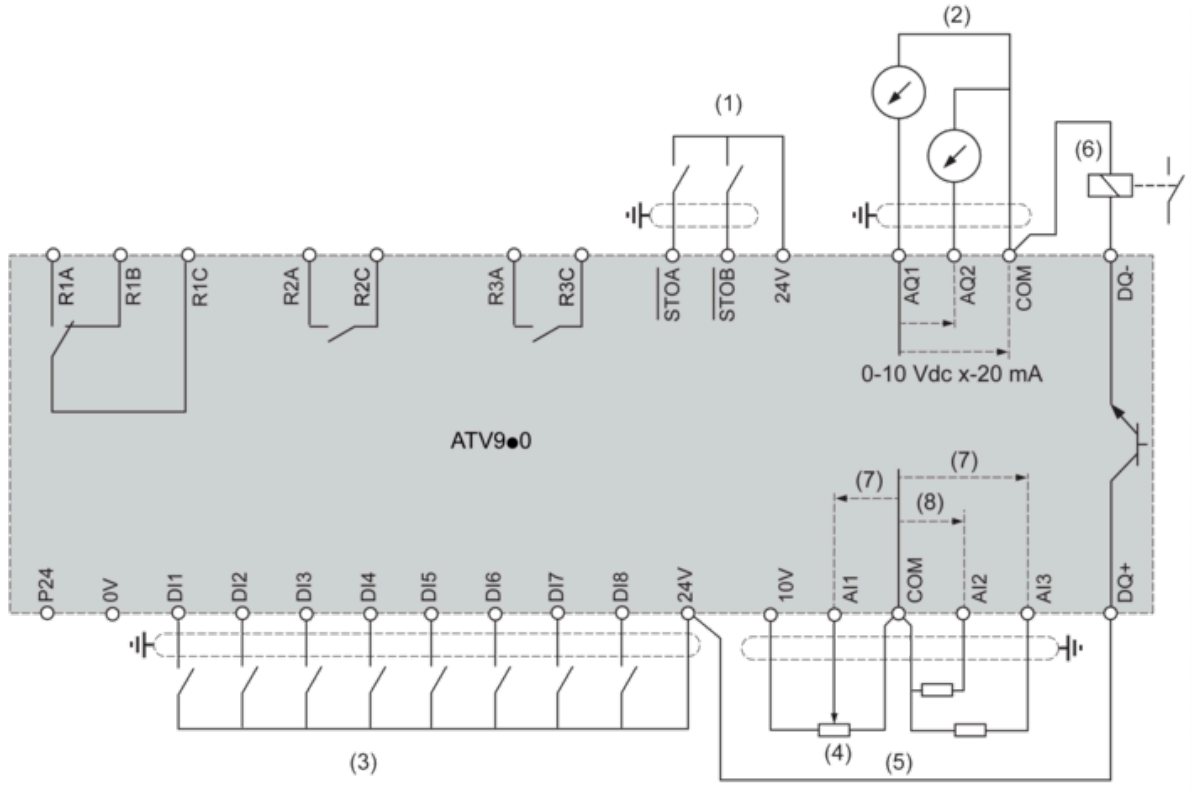
Three-Phase Power Supply with Downstream Breaking via Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



- (1) Line choke if used
(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.
- A1** : Drive
KM1 : Contactor

Control Block Wiring Diagram



- (1) Safe Torque Off
 - (2) Analog Output
 - (3) Digital Input
 - (4) Reference potentiometer
 - (5) Analog Input
 - (6) Digital Output
 - (7) 0-10 Vdc, x-20 mA
 - (8) 0-10 Vdc, -10 Vdc...+10 Vdc
- R1A, R1B, R1C :** Fault relay
R2A, R2C : Sequence relay
R3A, R3C : Sequence relay

Sensor Connection



It is possible to connect either 1 or 3 sensors on terminals AI1 or AI3

Sink / Source Switch Configuration

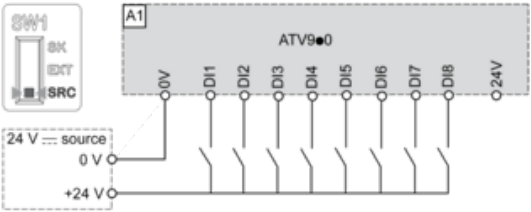
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

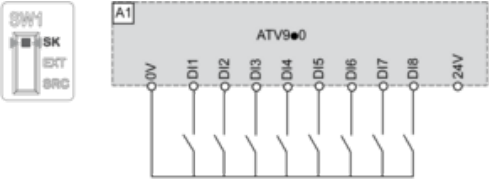
Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



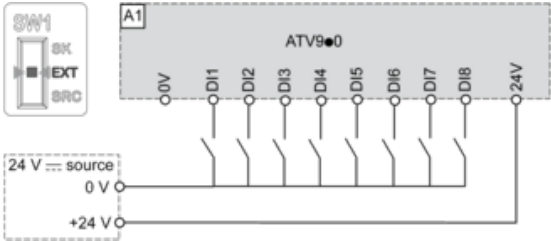
Switch Set to SRC (Source) Position and Use of an External Power Supply for the DI's



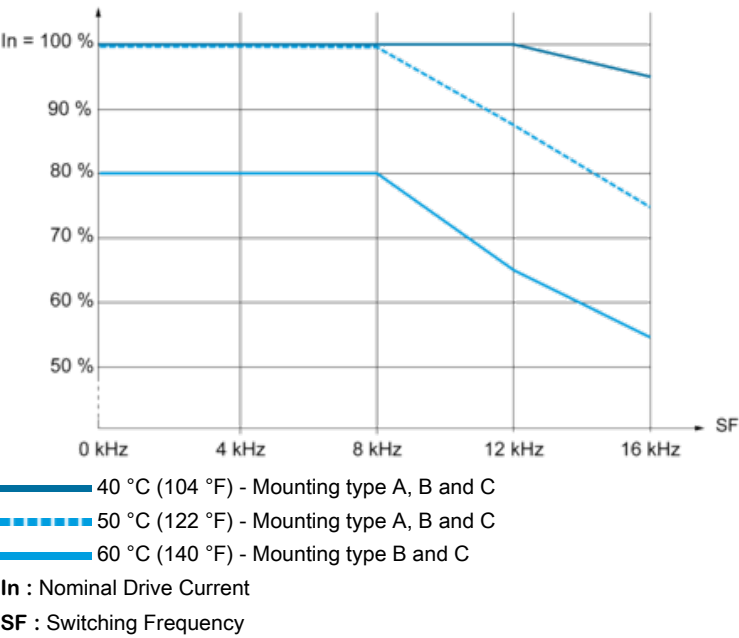
Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs



Switch Set to EXT Position Using an External Power Supply for the DI's



Derating Curves



Recommended replacement(s)