



variable speed drive ATV71 - 2.2kW - 690V - EMC filter-graphic terminal

ATV71HU22Y

Discontinued on: 01 February 2021

1 To be end-of-service on: 01 March 2028

Main

Range of product	Altivar 71
Product or component type	Variable speed drive
Product specific application	Complex, high-power machines
Component name	ATV71
Motor power kW	1.5 kW, 3 phases at 500 V 2.2 kW, 3 phases at 690 V
Motor power hp	2 hp, 3 phases at 575 V
Maximum motor cable length	10 m shielded cable 10 m unshielded cable
Power supply voltage	500690 V - 1510 %
Network number of phases	3 phases
Line current	3.2 A for 600 V 3 phases / 2 hp 3.8 A for 500 V 3 phases 1.5 kW 4 A for 690 V 3 phases 2.2 kW
EMC filter	Integrated
Assembly style	With heat sink
Variant	Reinforced version
Prospective line Isc	22 kA for 3 phases
Nominal output current	2.7 A at 4 kHz 575 V 3 phases / 2 hp 3.2 A at 4 kHz 500 V 3 phases 1.5 kW 4 A at 4 kHz 690 V 3 phases 2.2 kW
Maximum transient current	4.8 A for 60 s 3 phases 1.5 kW 5.28 A for 2 s 3 phases / 2 hp 5.28 A for 2 s 3 phases 2.2 kW
Output frequency	0.1500 Hz
Nominal switching frequency	4 kHz
Switching frequency	2.56 kHz adjustable 46 kHz with derating factor
Asynchronous motor control profile	Voltage/frequency ratio (2 or 5 points) Sensorless flux vector control (SFVC) (voltage or current vector) Flux vector control (FVC) with sensor (current vector) ENA (Energy adaptation) system for unbalanced loads
Type of polarization	No impedance for Modbus

Complementary

Complementary	
Product destination	Asynchronous motors Synchronous motors
Power supply voltage limits	425759 V
Power supply frequency	5060 Hz - 55 %
Power supply frequency limits	47.563 Hz
Speed range	1100 for asynchronous motor in open-loop mode, without speed feedback 11000 for asynchronous motor in closed-loop mode with encoder feedback 150 for synchronous motor in open-loop mode, without speed feedback
Speed accuracy	+/- 0.01 % of nominal speed in closed-loop mode with encoder feedback 0.2 Tn to Tn +/- 10 % of nominal slip without speed feedback 0.2 Tn to Tn
Torque accuracy	+/- 15 % in open-loop mode, without speed feedback +/- 5 % in closed-loop mode with encoder feedback
Transient overtorque	170 % of nominal motor torque +/- 10 % for 60 s every 10 minutes 220 % of nominal motor torque +/- 10 % for 2 s
Braking torque	<= 150 % with braking or hoist resistor 30 % without braking resistor
Synchronous motor control profile	Vector control without speed feedback
Regulation loop	Adjustable PI regulator
Motor slip compensation	Adjustable Suppressable Automatic whatever the load Not available in voltage/frequency ratio (2 or 5 points)
Diagnostic	1 LED (red) for drive voltage
Output voltage	<= power supply voltage
Insulation	Electrical between power and control
Type of cable for mounting in an enclosure	With a NEMA Type1 kit: 3 wire(s)UL 508 cable at 40 °C, copper 75 °C / PVC With an IP21 or an IP31 kit: 3 wire(s)IEC cable at 40 °C, copper 70 °C / PVC Without mounting kit: 1 wire(s)IEC cable at 45 °C, copper 70 °C / PVC Without mounting kit: 1 wire(s)IEC cable at 45 °C, copper 90 °C / XLPE/EPR
Electrical connection	Terminal, clamping capacity: 2.5 mm², AWG 14 (AI1-/AI1+, AI2, AO1, R1A, R1B, R1C, R2A, R2B, L11LI6, PWR) Terminal, clamping capacity: 50 mm², AWG 1/0 (L1/R, L2/S, L3/T, U/T1, V/T2, W/T3, PC/-, PO, PA/+, PA, PB)
Tightening torque	0.6 N.m (Al1-/Al1+, Al2, AO1, R1A, R1B, R1C, R2A, R2B, Ll1Ll6, PWR) 12 N.m, 102.2 lb.in (L1/R, L2/S, L3/T, U/T1, V/T2, W/T3, PC/-, PO, PA/+, PA, PB)
Supply	Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10 mA, protection type overload and short-circuit protection Internal supply: 24 V DC (2127 V), <200 mA, protection type: overload and short-circuit protection
Analogue input number	2
Analogue input type	Al1-/Al1+ bipolar differential voltage: +/- 10 V DC 24 V max, resolution 11 bits + sign Al2 software-configurable current: 020 mA, impedance: 242 Ohm, resolution 11 bits Al2 software-configurable voltage: 010 V DC 24 V max, impedance: 30000 Ohm, resolution 11 bits
Input sampling time	2 ms +/- 0.5 ms (Al1-/Al1+) - analog input(s) 2 ms +/- 0.5 ms (Al2) - analog input(s) 2 ms +/- 0.5 ms (Ll1Ll5) - discrete input(s) 2 ms +/- 0.5 ms (Ll6)if configured as logic input - discrete input(s)
Response time	<= 100 ms in STO (Safe Torque Off) AO1 2 ms, tolerance +/- 0.5 ms for analog output(s) R1A, R1B, R1C 7 ms, tolerance +/- 0.5 ms for discrete output(s) R2A, R2B 7 ms, tolerance +/- 0.5 ms for discrete output(s)
Absolute accuracy precision	+/- 0.6 % (Al1-/Al1+) for a temperature variation 60 °C +/- 0.6 % (Al2) for a temperature variation 60 °C +/- 1 % (AO1) for a temperature variation 60 °C
Linearity error	+/- 0.15 % of maximum value (AI1-/AI1+, AI2) +/- 0.2 % (AO1)
Analogue output number	1
Analogue output type	AO1 software-configurable logic output 10 V 20 mA AO1 software-configurable current 020 mA, impedance: 500 Ohm, resolution 10 bits

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Discrete output number	2
Discrete output type	Configurable relay logic: (R1A, R1B, R1C) NO/NC - 100000 cycles Configurable relay logic: (R2A, R2B) NO - 100000 cycles
Minimum switching current	3 mA at 24 V DC for configurable relay logic
Maximum switching current	R1, R2: 2 A at 250 V AC inductive load, cos phi = 0.4 R1, R2: 2 A at 30 V DC inductive load, cos phi = 0.4 R1, R2: 5 A at 250 V AC resistive load, cos phi = 1 R1, R2: 5 A at 30 V DC resistive load, cos phi = 1
Discrete input number	7
Discrete input type	LI1LI5: programmable 24 V DC with level 1 PLC, impedance: 3500 Ohm LI6: switch-configurable 24 V DC with level 1 PLC, impedance: 3500 Ohm LI6: switch-configurable PTC probe 06, impedance: 1500 Ohm PWR: safety input 24 V DC, impedance: 1500 Ohm conforming to ISO 13849-1 level d
Discrete input logic	Negative logic (sink) (LI1LI5), > 16 V (state 0), < 10 V (state 1) Positive logic (source) (LI1LI5), < 5 V (state 0), > 11 V (state 1) Negative logic (sink) (LI6)if configured as logic input, > 16 V (state 0), < 10 V (state 1) Positive logic (source) (LI6)if configured as logic input, < 5 V (state 0), > 11 V (state 1)
Acceleration and deceleration ramps	Automatic adaptation of ramp if braking capacity exceeded, by using resistor Linear adjustable separately from 0.01 to 9000 s S, U or customized
Braking to standstill	By DC injection
Protection type	Against exceeding limit speed: drive Against input phase loss: drive Break on the control circuit: drive Input phase breaks: drive Line supply overvoltage: drive Line supply undervoltage: drive Overcurrent between output phases and earth: drive Overheating protection: drive Overvoltages on the DC bus: drive Short-circuit between motor phases: drive Thermal protection: drive Motor phase break: motor Power removal: motor Thermal protection: motor
-	
Insulation resistance	> 1 mOhm 500 V DC for 1 minute to earth
Insulation resistance Frequency resolution	> 1 mOhm 500 V DC for 1 minute to earth Analog input: 0.024/50 Hz Display unit: 0.1 Hz
	Analog input: 0.024/50 Hz
Frequency resolution	Analog input: 0.024/50 Hz Display unit: 0.1 Hz
Frequency resolution Communication port protocol	Analog input: 0.024/50 Hz Display unit: 0.1 Hz CANopen Modbus 1 RJ45 (on front face) for Modbus 1 RJ45 (on terminal) for Modbus
Frequency resolution Communication port protocol Connector type	Analog input: 0.024/50 Hz Display unit: 0.1 Hz CANopen Modbus 1 RJ45 (on front face) for Modbus 1 RJ45 (on terminal) for Modbus Male SUB-D 9 on RJ45 for CANopen
Frequency resolution Communication port protocol Connector type Physical interface	Analog input: 0.024/50 Hz Display unit: 0.1 Hz CANopen Modbus 1 RJ45 (on front face) for Modbus 1 RJ45 (on terminal) for Modbus Male SUB-D 9 on RJ45 for CANopen 2-wire RS 485 for Modbus
Frequency resolution Communication port protocol Connector type Physical interface Transmission frame	Analog input: 0.024/50 Hz Display unit: 0.1 Hz CANopen Modbus 1 RJ45 (on front face) for Modbus 1 RJ45 (on terminal) for Modbus Male SUB-D 9 on RJ45 for CANopen 2-wire RS 485 for Modbus RTU for Modbus 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal 9600 bps, 19200 bps for Modbus on front face
Frequency resolution Communication port protocol Connector type Physical interface Transmission frame Transmission rate	Analog input: 0.024/50 Hz Display unit: 0.1 Hz CANopen Modbus 1 RJ45 (on front face) for Modbus 1 RJ45 (on terminal) for Modbus Male SUB-D 9 on RJ45 for CANopen 2-wire RS 485 for Modbus RTU for Modbus 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal 9600 bps, 19200 bps for Modbus on front face 20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps for CANopen 8 bits, 1 stop, even parity for Modbus on front face
Frequency resolution Communication port protocol Connector type Physical interface Transmission frame Transmission rate Data format	Analog input: 0.024/50 Hz Display unit: 0.1 Hz CANopen Modbus 1 RJ45 (on front face) for Modbus 1 RJ45 (on terminal) for Modbus Male SUB-D 9 on RJ45 for CANopen 2-wire RS 485 for Modbus RTU for Modbus 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal 9600 bps, 19200 bps for Modbus on front face 20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps for CANopen 8 bits, 1 stop, even parity for Modbus on front face 8 bits, odd even or no configurable parity for Modbus on terminal
Frequency resolution Communication port protocol Connector type Physical interface Transmission frame Transmission rate Data format Number of addresses	Analog input: 0.024/50 Hz Display unit: 0.1 Hz CANopen Modbus 1 RJ45 (on front face) for Modbus 1 RJ45 (on terminal) for Modbus Male SUB-D 9 on RJ45 for CANopen 2-wire RS 485 for Modbus RTU for Modbus 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal 9600 bps, 19200 bps for Modbus on front face 20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps for CANopen 8 bits, 1 stop, even parity for Modbus on front face 8 bits, odd even or no configurable parity for Modbus on terminal 1127 for CANopen 1247 for Modbus
Frequency resolution Communication port protocol Connector type Physical interface Transmission frame Transmission rate Data format Number of addresses Method of access	Analog input: 0.024/50 Hz Display unit: 0.1 Hz CANopen Modbus 1 RJ45 (on front face) for Modbus 1 RJ45 (on terminal) for Modbus Male SUB-D 9 on RJ45 for CANopen 2-wire RS 485 for Modbus RTU for Modbus 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal 9600 bps, 19200 bps for Modbus on front face 20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps for CANopen 8 bits, 1 stop, even parity for Modbus on front face 8 bits, odd even or no configurable parity for Modbus on terminal 1127 for CANopen 1247 for Modbus Slave CANopen
Frequency resolution Communication port protocol Connector type Physical interface Transmission frame Transmission rate Data format Number of addresses Method of access Marking	Analog input: 0.024/50 Hz Display unit: 0.1 Hz CANopen Modbus 1 RJ45 (on front face) for Modbus 1 RJ45 (on terminal) for Modbus Male SUB-D 9 on RJ45 for CANopen 2-wire RS 485 for Modbus RTU for Modbus 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal 9600 bps, 19200 bps for Modbus on front face 20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps for CANopen 8 bits, 1 stop, even parity for Modbus on front face 8 bits, odd even or no configurable parity for Modbus on terminal 1127 for CANopen 1247 for Modbus Slave CANopen
Frequency resolution Communication port protocol Connector type Physical interface Transmission frame Transmission rate Data format Number of addresses Method of access Marking Operating position	Analog input: 0.024/50 Hz Display unit: 0.1 Hz CANopen Modbus 1 RJ45 (on front face) for Modbus 1 RJ45 (on terminal) for Modbus Male SUB-D 9 on RJ45 for CANopen 2-wire RS 485 for Modbus RTU for Modbus 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal 9600 bps, 19200 bps for Modbus on front face 20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps for CANopen 8 bits, 1 stop, even parity for Modbus on front face 8 bits, odd even or no configurable parity for Modbus on terminal 1127 for CANopen 1247 for Modbus Slave CANopen CE Vertical +/- 10 degree
Frequency resolution Communication port protocol Connector type Physical interface Transmission frame Transmission rate Data format Number of addresses Method of access Marking Operating position Height	Analog input: 0.024/50 Hz Display unit: 0.1 Hz CANopen Modbus 1 RJ45 (on front face) for Modbus 1 RJ45 (on terminal) for Modbus Male SUB-D 9 on RJ45 for CANopen 2-wire RS 485 for Modbus RTU for Modbus 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal 9600 bps, 19200 bps for Modbus on front face 20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps for CANopen 8 bits, 1 stop, even parity for Modbus on front face 8 bits, odd even or no configurable parity for Modbus on terminal 1127 for CANopen 1247 for Modbus Slave CANopen CE Vertical +/- 10 degree 420 mm
Frequency resolution Communication port protocol Connector type Physical interface Transmission frame Transmission rate Data format Number of addresses Method of access Marking Operating position Height Depth	Analog input: 0.024/50 Hz Display unit: 0.1 Hz CANopen Modbus 1 RJ45 (on front face) for Modbus 1 RJ45 (on terminal) for Modbus Male SUB-D 9 on RJ45 for CANopen 2-wire RS 485 for Modbus RTU for Modbus 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal 9600 bps, 19200 bps for Modbus on front face 20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps for CANopen 8 bits, 1 stop, even parity for Modbus on front face 8 bits, odd even or no configurable parity for Modbus on terminal 1127 for CANopen 1247 for Modbus Slave CANopen CE Vertical +/- 10 degree 420 mm

Communication card for EtherNet/IP
Communication card for Fipio
I/O extension card
Communication card for Interbus-S
Interface card for encoder
Communication card for Modbus Plus
Communication card for Modbus TCP
Communication card for Modbus/Uni-Telway
Overhead crane card
Communication card for Profibus DP
Communication card for Profibus DP V1

Environment

Noise level	59.9 dB conforming to 86/188/EEC					
Dielectric strength	3110 V DC between earth and power terminals 5345 V DC between control and power terminals					
Electromagnetic compatibility	1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11					
Standards	EN 61800-3 environments 1 category C3 EN 55011 class A group 2 EN 61800-3 environments 2 category C3 EN/IEC 61800-3 EN/IEC 61800-5-1 IEC 60721-3-3 class 3C2 UL Type 1					
Product certifications	CSA NOM 117 C-Tick UL GOST					
Pollution degree	2 conforming to EN/IEC 61800-5-1 3 conforming to UL 840					
IP degree of protection	IP20 on upper part without blanking plate on cover conforming to EN/IEC 60529 IP20 on upper part without blanking plate on cover conforming to EN/IEC 61800-5-1 IP21 conforming to EN/IEC 60529 IP21 conforming to EN/IEC 61800-5-1 IP41 on upper part conforming to EN/IEC 60529 IP41 on upper part conforming to EN/IEC 61800-5-1 IP54 on lower part conforming to EN/IEC 60529 IP54 on lower part conforming to EN/IEC 61800-5-1					
Vibration resistance	1 gn (f= 13200 Hz) conforming to EN/IEC 60068-2-6 1.5 mm peak to peak (f= 313 Hz) conforming to EN/IEC 60068-2-6					
Shock resistance	15 gn for 11 ms conforming to EN/IEC 60068-2-27					
Relative humidity	595 % without condensation conforming to IEC 60068-2-3 595 % without dripping water conforming to IEC 60068-2-3					
Ambient air temperature for operation	-1050 °C (without derating)					
Ambient air temperature for storage	-2570 °C					
Operating altitude	<= 1000 m without derating 10002260 m with current derating 1 % per 100 m					

Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	24.0 cm
Package 1 Width	40.0 cm
Package 1 Length	60.0 cm
Package 1 Weight	36.75 kg
Unit Type of Package 2	P06
Number of Units in Package 2	2

77.0 cm
60.0 cm
80.0 cm
82.0 kg
Green Premium product
Pro-active compliance (Product out of EU RoHS legal scope) EU RoHS Declaration
Yes
China RoHS declaration
Yes
Product Environmental Profile
End of Life Information
The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins
WARNING: This product can expose you to chemicals including: Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm. For more information go to www.P65Warnings.ca.gov

Contractual warranty

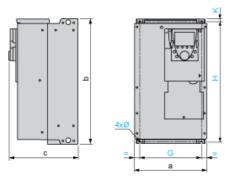
Warranty 18 months

ATV71HU22Y

Dimensions Drawings

UL Type 1/IP 20 Drives

Dimensions without Option Card



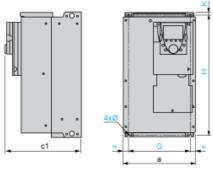
Dimensions in mm

а	b	С	G	Н	К	Ø
240	420	236	206	403	11	6

Dimensions in in.

а	b	С	G	Н	К	Ø
9.44	16.54	9.29	8.11	15.87	0.45	0.23

Dimensions with 1 Option Card (1)



Dimensions in mm

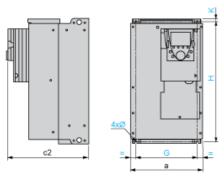
а	c1	G	Н	К	Ø
240	259	206	403	11	6

Dimensions in in.

а	c1	G	Н	К	Ø
9.44	10.20	8.11	15.87	0.45	0.23

⁽¹⁾ Option cards: I/O extension cards, communication cards or "Controller Inside" programmable card.

Dimensions with 2 Option Cards (1)



Dimensions in mm

а	c2	G	Н	К	Ø
240	282	206	403	11	6

Dimensions in in.

a	a	c2	G	Н	К	Ø
ć	9.44	11.10	8.11	15.87	0.45	0.23

⁽¹⁾ Option cards: I/O extension cards, communication cards or "Controller Inside" programmable card.

ATV71HU22Y

Mounting and Clearance

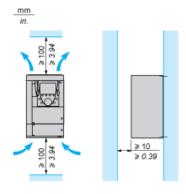
Mounting Recommendations

Depending on the conditions in which the drive is to be used, its installation will require certain precautions and the use of appropriate accessories.

Install the unit vertically:

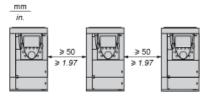
- Avoid placing it close to heating elements
- Leave sufficient free space to ensure that the air required for cooling purposes can circulate from the bottom to the top of the unit.

Clearance

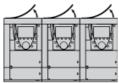


Mounting Types

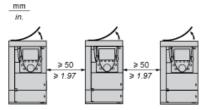
Type A Mounting



Type B Mounting



Type C Mounting



By removing the protective blanking cover from the top of the drive, the degree of protection for the drive becomes IP 20.

The protective blanking cover may vary according to the drive model (refer to the user guide).

The protective blanking cover must be removed from ATV 71P•••N4Z drives when they are mounted in a dust and damp proof enclosure.

ATV71HU22Y

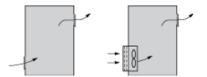
Mounting and Clearance

Specific Recommendations for Mounting the Drive in an Enclosure

Ventilation

To ensure proper air circulation in the drive:

- Fit ventilation grilles.
- Ensure that there is sufficient ventilation. If there is not, install a forced ventilation unit with a filter. The openings and/or fans must provide a flow rate a



- Use special filters with IP 54 protection.
- Remove the blanking cover from the top of the drive.

Dust and Damp Proof Metal Enclosure (IP 54)

The drive must be mounted in a dust and damp proof enclosure in certain environmental conditions: dust, corrosive gases, high humidity with risk of condensation and dripping water, splashing liquid, etc.

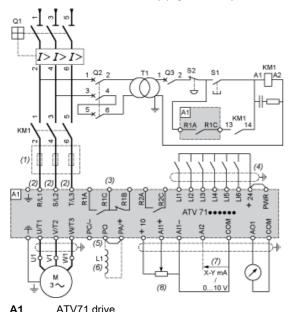
This enables the drive to be used in an enclosure where the maximum internal temperature reaches 50°C.

ATV71HU22Y

Connections and Schema

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

Three-Phase Power Supply with Upstream Breaking via Contactor



A1 KM1 Contactor L1 DC choke Q1 Circuit-breaker

Q2 GV2 L rated at twice the nominal primary current of T1

Q3 GB2CB05

S1, S2 XB4 B or XB5 A pushbuttons

T1 100 VA transformer 220 V secondary

(1) (2) Line choke (three-phase); mandatory for ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).

For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections

(3) Fault relay contacts. Used for remote signalling of the drive status.

Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supp

(4) (5) There is no PO terminal on ATV71HC11Y...HC63Y drives.

(6) Optional DC choke for ATV71H•••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of

(7) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.

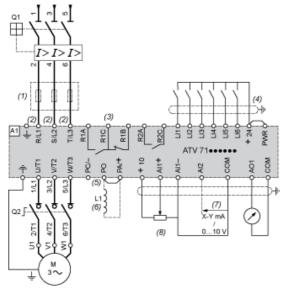
(8) Reference potentiometer.

ATV71HU22Y

Connections and Schema

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

Three-Phase Power Supply with Downstream Breaking via Switch Disconnector



- **A1** ATV71 drive
- L1 DC choke
- Q1 Circuit-breaker
- Q2 Switch disconnector (Vario)
- (1) (2)
- Line choke (three-phase), mandatory for ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)). For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections
- Fault relay contacts. Used for remote signalling of the drive status.
- Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supp
- There is no PO terminal on ATV71HC11Y...HC63Y drives.

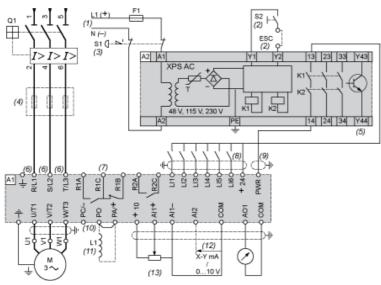
 Optional DC choke for ATV71H••••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of
- (3) (4) (5) (6) (7) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (8) Reference potentiometer.

ATV71HU22Y

Connections and Schema

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 0 According to IEC/EN 60204-1

Three-Phase Power Supply, Low Inertia Machine, Vertical Movement



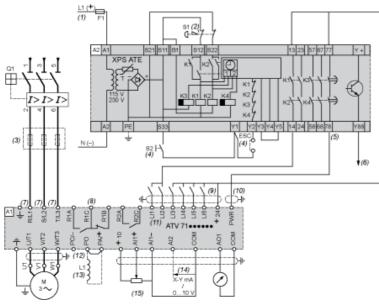
- Α2 Preventa XPS AC safety module for monitoring emergency stops and switches. One safety module can manage the "Power Removal" function for
- L1 DC choke
- Q1 Circuit-breaker
- **S1** Emergency stop button with 2 contacts
- S2 XB4 B or XB5 A pushbutton
- (1) Power supply: 24 Vdc or Vac, 48 Vac, 115 Vac, 230 Vac.
- (2) S2: resets XPS AC module on power-up or after an emergency stop. ESC can be used to set external starting conditions.
- (3) Requests freewheel stopping of the movement and activates the "Power Removal" safety function.
- Line choke (three-phase), mandatory for and ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).
- (4) (5) (6) (7) The logic output can be used to signal that the machine is in a safe stop state.
- For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections
- Fault relay contacts. Used for remote signalling of the drive status.
- Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supp Standardized coaxial cable, type RG174/U according to MIL-C17 or KX3B according to NF C 93-550, external diameter 2.54 mm /0.09 in., maxim (8)
- (9)
- (10)There is no PO terminal on ATV71HC11Y...HC63Y drives.
- Optional DC choke for ATV71H••••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of (11)
- (12)Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (13)Reference potentiometer.

ATV71HU22Y

Connections and Schema

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 1 According to IEC/EN 60204-1

Three-Phase Power Supply, High Inertia Machine



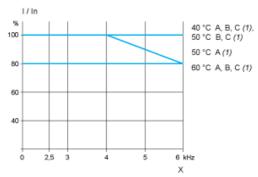
- **A1** ATV71 drive
- A2 (5) F1 Preventa XPS ATE safety module for monitoring emergency stops and switches. One safety module can manage the "Power Removal" safety fu
- Fuse
- L1 DC choke
- Q1 Circuit-breaker
- **S1** Emergency stop button with 2 N/C contacts
- S2 Run button
- (1) (2) (3) Power supply: 24 Vdc or Vac. 115 Vac. 230 Vac.
- Requests controlled stopping of the movement and activates the "Power Removal" safety function.
- Line choke (three-phase), mandatory for ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).
- (4) (5) S2: resets XPS ATE module on power-up or after an emergency stop. ESC can be used to set external starting conditions.
- For stopping times requiring more than 30 seconds in category 1, use a Preventa XPS AV safety module which can provide a maximum time del
- (6) The logic output can be used to signal that the machine is in a safe state.
- (7)For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections
- (8) Fault relay contacts. Used for remote signalling of the drive status.
- (9) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supp
- (10)Standardized coaxial cable, type RG174/U according to MIL-C17 or KX3B according to NF C 93-550, external diameter 2.54 mm/0.09 in., maxim
- (11)Logic inputs LI1 and LI2 must be assigned to the direction of rotation: LI1 in the forward direction and LI2 in the reverse direction.
- (12)There is no PO terminal on ATV71HC11Y...HC63Y drives.
- (13)Optional DC choke for ATV71H•••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of
- (14)Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (15)Reference potentiometer.

ATV71HU22Y

Performance Curves

Derating Curves

The derating curves for the drive nominal current (In) depend on the temperature, the switching frequency and the mounting type. For intermediate temperatures (e.g. 55°C), interpolate between 2 curves.



- X Switching frequency
- (1) Mounting type

Above 50°C, the drive should be fitted with a control card fan kit.

Recommended replacement(s)

ATV71HU22Y is replaced by:

1x



Variable speed drive, Altivar Process ATV900, ATV930, 3 kW, 500V/690 V, IP00 ATV930U30Y6