## Data sheet 6ES7677-2DB42-0GB0



SIMATIC ET 200SP Open Controller, CPU 1515SP PC2, 8 GB RAM (basic device 6ES7677-2DB40-0AA0), 128 GB CFast with Windows 10 IoT Enterprise LTSC 2019 64-bit, and S7-1500 software Controller CPU 1505SP V2x preinstalled; interfaces: 1x slot CFast, 1x slot SD/MMC, 1x connection for ET 200SP BusAdapter PROFINET, 1x 10/100/1000 Mbps Ethernet, 2x USB 3.0; 2x USB 2.0, 1x DisplayPort; documentation on CFast, restore image on CFast

General information	
Product type designation	CPU 1515SP PC2
HW functional status	from FS04
Firmware version	V21.9
Engineering with	
STEP 7 TIA Portal configurable/integrated from version	V17
Installed software	
<ul> <li>Visualization</li> </ul>	No
Control	S7-1500 Software Controller CPU 1505SP
Configuration control	
via dataset	Yes
Control elements	
Mode selector switch	1
Supply voltage	
Rated value (DC)	24 V
permissible range, lower limit (DC)	19.2 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
<ul> <li>Mains/voltage failure stored energy time</li> </ul>	5 ms
Input current	
Current consumption (rated value)	1.8 A; Full processor load, incl. ET 200SP modules and using USB
Current consumption (in no-load operation), typ.	0.5 A
Current consumption, max.	2.9 A
l²t	0.426 A <sup>2</sup> ·s; with starting current inrush
Power	
Active power input, max.	43 W; incl. ET 200SP modules and using USB
Infeed power to the backplane bus	8.75 W
Power loss	
Power loss, typ.	15 W; without ET 200SP modules and without using USB
Processor	
Processor type	Intel Atom E3940, 1.6 GHz, 4 cores
Memory	
Type of memory	DDR3L
Main memory	8 GB RAM
CFast memory card	Yes; 128 GB flash memory
SIMATIC memory card required	No
Work memory	
<ul><li>integrated (for program)</li></ul>	1 Mbyte
<ul><li>integrated (for data)</li></ul>	5 Mbyte

• integrated (for CPU function library of CPU Runtime)	20 Mbyte
	20 Mbyte
Load memory  • integrated (on PC mass storage)	320 Mbyte
	320 Mbyte
Backup	Voc. all mamony group declared retentive
with UPS	Yes; all memory areas declared retentive
with non-volatile memory	Yes
CPU-blocks	
Number of elements (total)	6 000; In addition to blocks such as DBs, FBs and FCs, UDTs, global constants, etc. are also regarded as elements
DB	oniotante, etc. are also regulated as demonte
Number, max.	5 999; Number range: 1 to 65535
• Size, max.	5 Mbyte
FB	3 Millyto
Number, max.	5 998; Number range: 1 to 65535
• Size, max.	1 024 kbyte
FC	1 024 kDyte
	5 000: Number range: 1 to 65525
• Number, max.	5 999; Number range: 1 to 65535
• Size, max.	1 024 kbyte
OB	1 024 khyto
• Size, max.	1 024 kbyte
Number of free cycle OBs	100
Number of time alarm OBs	20
Number of delay alarm OBs	20
Number of cyclic interrupt OBs	20
<ul> <li>Number of process alarm OBs</li> </ul>	50
<ul> <li>Number of DPV1 alarm OBs</li> </ul>	3
<ul> <li>Number of isochronous mode OBs</li> </ul>	1
<ul> <li>Number of technology synchronous alarm OBs</li> </ul>	2
<ul> <li>Number of startup OBs</li> </ul>	100
<ul> <li>Number of asynchronous error OBs</li> </ul>	4
<ul> <li>Number of synchronous error OBs</li> </ul>	2
Number of diagnostic alarm OBs	1
Nesting depth	
<ul> <li>per priority class</li> </ul>	24
Counters, timers and their retentivity	
S7 counter	
Number	2 048
Retentivity	
— adjustable	Yes
IEC counter	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
S7 times	
Number	2 048
Retentivity	
— adjustable	Yes
— adjustable  IEC timer	100
Number	Any (only limited by the main moment)
	Any (only limited by the main memory)
Retentivity	Von
— adjustable	Yes
Data areas and their retentivity	MALL LE LANGE LANG
Retentive data area (incl. timers, counters, flags), max.	410 kbyte; For storage in NVRAM; for storage in mass storage 5 242 020 bytes
Flag	
• Size, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	
<ul> <li>Retentivity adjustable</li> </ul>	Yes
Retentivity preset	No
Local data	
<ul> <li>per priority class, max.</li> </ul>	64 kbyte; max. 16 KB per block

Address area	
Number of IO modules	8 192
I/O address area	
• Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All outputs are in the process image
Subprocess images	
Number of subprocess images, max.	32
Hardware configuration	VL
	Yes
Integrated power supply  Number of distributed IO systems	20
·	20
Number of DP masters	
• Via CM	1
Number of IO Controllers	
• via PC interfaces	1
Rack	
<ul> <li>Modules per rack, max.</li> </ul>	64; CPU 1515SP PC + 64 modules + server module
<ul> <li>Quantity of operable ET 200SP modules, max.</li> </ul>	64
<ul> <li>Quantity of operable ET 200AL modules, max.</li> </ul>	16
Number of lines, max.	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available
	slots
Time of day	
Clock	
• Type	Hardware clock
<ul> <li>Hardware clock (real-time)</li> </ul>	Yes; Resolution: 1 s
Backup time	6 wk; At 40 °C ambient temperature, typically
<ul> <li>Deviation per day, max.</li> </ul>	10 s; Typ.: 2 s
Clock synchronization	
• supported	Yes
• to DP, master	Yes
on Ethernet via NTP	Yes
on Windows clock, device	Yes
Interfaces	
Number of industrial Ethernet interfaces	2
Number of PROFINET interfaces	1
Number of PROFIBUS interfaces	1
Number of RS 485 interfaces	1; Via CM DP module
Number of USB interfaces	4; 2x USB 2.0, 2x USB 3.0 on front side
Number of SD card slots	1
Video interfaces	
Graphics interface	1x DisplayPort
1. Interface	
Interface type	PROFINET
automatic detection of transmission rate	Yes
Autonegotiation	Yes
Autocrossing	Yes
Number of connections	88
Interface types	
• RJ 45 (Ethernet)	Yes; Via BusAdapter BA 2x RJ45
— Transmission rate, max.	100 Mbit/s
— Industrial Ethernet status LED	Yes
Number of ports	2
integrated switch	Yes
BusAdapter (PROFINET)	Yes; compatible BusAdapters: BA 2x RJ45, BA 2x M12, BA 2x FC, BA 2x LC,
□ Duanuapici (I'NOFINET)	BA LC/RJ45, BA LC/FC, BA 2x SCRJ, BA SCRJ/RJ45, BA SCRJ/FC,
Protocols	
• IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
	100

Open IE communication	Yes; Optionally also encrypted
Web server	Yes
PROFINET IO Controller	
Services	
— Isochronous mode	Yes
<ul><li>shortest clock pulse</li></ul>	500 µs
— IRT	Yes
— PROFlenergy	Yes
— Prioritized startup	Yes; max. 32 PROFINET devices; if you want to use the "Prioritized startup" functionality in STEP 7 for the PROFINET interface of the CPU, the CPU and the device must be separated by means of a switch (e.g. SCALANCE)
<ul> <li>Number of connectable IO Devices, max.</li> </ul>	128
<ul> <li>Of which IO devices with IRT, max.</li> </ul>	64
— of which in line, max.	64
<ul> <li>Number of connectable IO Devices for RT, max.</li> </ul>	128
— of which in line, max.	128
<ul> <li>Number of IO Devices that can be simultaneously activated/deactivated, max.</li> </ul>	8
<ul> <li>IO Devices changing during operation (partner ports), supported</li> </ul>	Yes
<ul> <li>Number of IO Devices per tool, max.</li> </ul>	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
Update time for IRT	
— for send cycle of 500 μs	500 µs to 8 ms
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
With IRT and parameterization of "odd" send cycles	Update time = set "odd" send clock (any multiple of 125 $\mu s$ : 625 $\mu s$ 3 875 $\mu s)$ minimum cycle time start from 500 $\mu s$
Update time for RT	
— for send cycle of 500 μs	500 μs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
Address area	
— Inputs, max.	8 kbyte
— Outputs, max.	8 kbyte
PROFINET IO Device	
Services	
— Isochronous mode	No
— shortest clock pulse	500 μs
— IRT	Yes
— PROFlenergy	Yes
— Prioritized startup	Yes
— Shared device	Yes
Number of IO Controllers with shared device, max.	4
Asset management record	Yes
2. Interface	
Interface type	Integrated Ethernet interface
automatic detection of transmission rate	Yes
Autonegotiation	Yes
Autocrossing	Yes
Interface types	
• RJ 45 (Ethernet)	Yes; Integrated
— Transmission rate, max.	1 000 Mbit/s
<ul> <li>Industrial Ethernet status LED</li> </ul>	No
Number of ports	1
3. Interface	
Interface type	PROFIBUS with CM DP
Number of connections	44
Interface types	

- DC 405	Voc
• RS 485	Yes
Protocols	Ver
PROFIBUS DP master	Yes
PROFIBUS DP device	Yes
SIMATIC communication	Yes
PROFIBUS DP master	
max. number of DP devices	125
Services	
— Equidistance	No
— Isochronous mode	No
Address area	
— Inputs, max.	8 kbyte
— Outputs, max.	8 kbyte
Interface types	
RS 485	
Transmission rate, max.	12 Mbit/s
Protocols	
PROFIsafe	No
Number of connections	
<ul> <li>Number of connections, max.</li> </ul>	88
<ul> <li>Number of connections reserved for ES/HMI/web</li> </ul>	10
Number of S7 routing paths	16
Redundancy mode	
Media redundancy	
— MRP	Yes
— MRPD	Yes
<ul> <li>Switchover time on line break, typ.</li> </ul>	200 ms
<ul> <li>Number of stations in the ring, max.</li> </ul>	50
SIMATIC communication	
<ul> <li>PG/OP communication</li> </ul>	Yes
S7 routing	Yes
<ul> <li>S7 communication, as server</li> </ul>	Yes
<ul> <li>S7 communication, as client</li> </ul>	Yes
User data per job, max.	64 kbyte; BSEND/BRCV: 64 KB; PUT/GET: 960 bytes
Open IE communication	
• TCP/IP	Yes
— Data length, max.	64 kbyte
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	2 048 byte
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
Web server	
• HTTP	Yes; Via Windows and PROFINET interface
• HTTPS	Yes; Via Windows and PROFINET interface
OPC UA	
Runtime license required	Yes; "Small" license required
OPC UA Client	Yes; From SW CPU 1505SP V2.6
OPC UA Server	Yes; Data access (read, write, subscribe), runtime license required
<ul> <li>Application authentication</li> </ul>	Yes; Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— Security policies	Yes; Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— User authentication	Yes; "anonymous" or by user name & password
Further protocols	
MODBUS	Yes; MODBUS TCP
S7 message functions	
Number of login stations for message functions, max.	32
Program alarms	Yes

Number of configurable program messages, max.	10 000
Number of simultaneously active program alarms	1 000
<ul> <li>Number of program alarms</li> </ul>	1 000
<ul> <li>Number of alarms for system diagnostics</li> </ul>	200
<ul> <li>Number of alarms for motion technology objects</li> </ul>	160
Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 8 engineering systems
Status block	Yes; up to 8 simultaneously
Single step	No
Number of breakpoints	8
Status/control	
<ul> <li>Status/control variable</li> </ul>	Yes
<ul><li>Variables</li></ul>	Inputs, outputs, memory bits, DB, times, counters
<ul> <li>Number of variables, max.</li> </ul>	
<ul><li>of which status variables, max.</li></ul>	200
<ul><li>of which control variables, max.</li></ul>	200
Forcing	
• Forcing	Yes
<ul> <li>Forcing, variables</li> </ul>	Inputs, outputs
Number of variables, max.	200
Diagnostic buffer	
• present	Yes
<ul> <li>Number of entries, max.</li> </ul>	1 000
— of which powerfail-proof	300
Traces	
<ul> <li>Number of configurable Traces</li> </ul>	4
<ul> <li>Memory size per trace, max.</li> </ul>	512 kbyte
Interrupts/diagnostics/status information	
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
Supported technology objects	
Motion Control	Yes; Note: The number of technology objects affects the cycle time of the PLC
Number of available Motion Control resources for technology objects.	program; selection guide via the TIA Selection Tool 2 400
technology objects	2 400
Required Motion Control resources	2 400
	40; per axis
Required Motion Control resources	
<ul> <li>Required Motion Control resources</li> <li>per speed-controlled axis</li> </ul>	40; per axis
<ul> <li>Required Motion Control resources</li> <li>— per speed-controlled axis</li> <li>— per positioning axis</li> </ul>	40; per axis 80; per axis
<ul> <li>Required Motion Control resources</li> <li>— per speed-controlled axis</li> <li>— per positioning axis</li> <li>— per synchronous axis</li> </ul>	40; per axis 80; per axis 160; per axis
<ul> <li>Required Motion Control resources</li> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per synchronous axis</li> <li>per external encoder</li> </ul>	40; per axis 80; per axis 160; per axis 80; per external encoder
<ul> <li>Required Motion Control resources</li> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per synchronous axis</li> <li>per external encoder</li> <li>per output cam</li> </ul>	40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam
<ul> <li>Required Motion Control resources</li> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per synchronous axis</li> <li>per external encoder</li> <li>per output cam</li> <li>per cam track</li> </ul>	40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track
<ul> <li>Required Motion Control resources         <ul> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per synchronous axis</li> <li>per external encoder</li> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> </ul> </li> <li>Positioning axis         <ul> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> </ul> </li> </ul>	40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe
<ul> <li>Required Motion Control resources         <ul> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per synchronous axis</li> <li>per external encoder</li> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> </ul> </li> <li>Positioning axis         <ul> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul> </li> </ul>	40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe
Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller	40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe
Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact	40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe  15 30  Yes; Universal PID controller with integrated optimization
Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_3Step	40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe  15 30  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_Step  PID-Temp	40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe  15 30  Yes; Universal PID controller with integrated optimization
Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_Step  PID-Temp  Counting and measuring	40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe  15 30  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_3Step  PID-Temp  Counting and measuring  High-speed counter	40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe  15 30  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_Step  PID-Temp  Counting and measuring  High-speed counter  Standards, approvals, certificates	40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe  15 30  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_Step  PID-Temp  Counting and measuring  High-speed counter  Standards, approvals, certificates  CE mark	40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe  15 30  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_Step  PID-Temp  Counting and measuring  High-speed counter  Standards, approvals, certificates  CE mark  CSA approval	40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe  15 30  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Yes  Yes
Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_Step  PID-Temp  Counting and measuring  High-speed counter  Standards, approvals, certificates  CE mark  CSA approval  cULus	40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe  15 30  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Yes  Yes Yes Yes
Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_Step  PID-Temp  Counting and measuring  High-speed counter  Standards, approvals, certificates  CE mark  CSA approval	40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe  15 30  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Yes  Yes

Ambient conditions	
Ambient temperature during operation	
• min.	-20 °C
• horizontal installation, min.	-20 °C
• horizontal installation, max.	$60~^{\circ}\text{C};$ from 55°C: with max. 32 ET 200SP modules; 4x 0.3 A USB load; CFast memory card max. 10% load; SD card not used
<ul> <li>vertical installation, min.</li> </ul>	-20 °C
vertical installation, max.	50 °C; from 45°C: with max. 32 ET 200SP modules; 4x 0.3 A USB load; CFast memory card and SD card; max. 10% load
Ambient temperature during storage/transportation	
• min.	-40 °C
• max.	70 °C
Vibrations	
Operation, tested according to IEC 60068-2-6	Yes
<ul> <li>Transport, tested acc. to IEC 60068-2-6</li> </ul>	Yes
Shock testing	
• tested according to IEC 60068-2-6	Yes
• tested according to IEC 60068-2-27	Yes
tested according to IEC 60068-2-29     tested according to IEC 60068-2-29	Yes
Storage/transport, tested acc. to IEC 60068-2-27	Yes
Operating systems	
pre-installed operating system	Windows 10 IoT Enterprise 2010 LTSC 64 bit MUII
configuration / header	Windows 10 IoT Enterprise 2019 LTSC, 64 bit, MUI
configuration / programming / header	
Programming language	
— LAD	Yes
— FBD	Yes
— STL	Yes
— SCL	Yes
— CFC	No
— GRAPH	Yes
Know-how protection	
<ul> <li>User program protection/password protection</li> </ul>	Yes
<ul> <li>Copy protection</li> </ul>	Yes
Block protection	Yes
Access protection	
protection of confidential configuration data	Yes
Protection level: Write protection	Yes
Protection level: Read/write protection	Yes
Protection level: Complete protection	Yes
programming / cycle time monitoring / header	
• lower limit	adjustable minimum cycle time
• upper limit	adjustable maximum cycle time
Open Development interfaces	aujando maximum vyolo amo
Size of ODK SO file, max.	5.8 Mbyte
Peripherals/Options	o.o mbyto
	Optionally for additional mass storage
SD card	Optionally for additional mass storage
Dimensions	
Width	160 mm
Height	117 mm
Depth	75 mm
Weights	
Weight, approx.	0.83 kg
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