Data sheet



SIPLUS ET 200SP CPU 1515SP PC2 F based on 6ES7677-2SB42-0GB0 with conformal coating, -40...+60 °C, 8 GB RAM, 128 GB CFast with Windows 10 IoT Enterprise 64-bit and S7-1500 Software Controller CPU 1505SP F preinstalled, interfaces: 1x slot CFast, 1x slot SD/MMC, 1x connection for ET 200SP BusAdapter PROFINET, 1x 10/100/1000 Mbps Ethernet 2x USB 3.0; 2x USB 2.0, 1x DisplayPort, documentation on USB flash drive, restore USB flash drive

General information	
Product type designation	CPU 1515SP PC2 F
based on	6ES7677-2SB42-0GB0
Engineering with	
 STEP 7 TIA Portal configurable/integrated from version 	see entry ID: 109746275
Installed software	
 Visualization 	No
 Control 	S7-1500 Software Controller CPU 1505SP F
Configuration control	
via dataset	Yes
Control elements	
Mode selector switch	1
Supply voltage	
Rated value (DC)	24 V
permissible range, lower limit (DC)	19.2 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
 Mains/voltage failure stored energy time 	5 ms
Input current	
Current consumption (rated value)	1.8 A; Full processor load, incl. ET 200SP modules and using USB
Current consumption (in no-load operation), typ.	0.5 A
Current consumption, max.	2.9 A
l²t	0.426 A ² ·s; with starting current inrush
Power	
Active power input, max.	43 W; incl. ET 200SP modules and using USB
Infeed power to the backplane bus	8.75 W
Power loss	
Power loss, typ.	16 W
Processor	
Processor type	Intel Atom E3940, 1.6 GHz, 4 cores
Memory	
Type of memory	DDR3L
Main memory	8 GB RAM
CFast memory card	Yes; 30 GB flash memory
SIMATIC memory card required	No
Work memory	
• integrated (for program)	1.5 Mbyte
integrated (for data)	5 Mbyte

• integrated (for CPU function library of CPU Runtime)	20 Mbyte
Load memory	20
• integrated (on PC mass storage)	320 Mbyte
Backup	
• with UPS	Yes; all memory areas declared retentive
with non-volatile memory	Yes
CPU processing times	
for bit operations, typ.	10 ns
for word operations, typ.	12 ns
for fixed point arithmetic, typ.	16 ns
for floating point arithmetic, typ.	64 ns
CPU-blocks	04 115
Number of elements (total)	6 000; In addition to blocks such as DBs, FBs and FCs, UDTs, global
Number of elements (total)	constants, etc. are also regarded as elements
DB	
Number, max.	5 999; Number range: 1 to 65535
• Size, max.	5 Mbyte
FB	
Number, max.	5 998; Number range: 1 to 65535
• Size, max.	1 024 kbyte
FC	
Number, max.	5 999; Number range: 1 to 65535
• Size, max.	1 024 kbyte
OB	
• Size, max.	1 024 kbyte
Number of free cycle OBs	100
Number of time alarm OBs	20
Number of delay alarm OBs	20
Number of cyclic interrupt OBs	20
Number of process alarm OBs	50
Number of DPV1 alarm OBs	3
 Number of isochronous mode OBs 	1
 Number of technology synchronous alarm OBs 	2
Number of startup OBs	100
Number of asynchronous error OBs	4
Number of synchronous error OBs	2
Number of diagnostic alarm OBs	1
Nesting depth	
per priority class	24; Up to 8 possible for F-blocks
Counters, timers and their retentivity	2., 60 to 6 possible to 1 possible
S7 counter	
• Number	2 048
Retentivity	
— adjustable	Yes
— adjustable IEC counter	
Number	Any (only limited by the main memory)
1 11	Arty (only limited by the main memory)
Retentivity — adjustable	Yes
S7 times	
• Number	2 048
Retentivity	
— adjustable	Yes
— adjustable	
Number	Any (only limited by the main memory)
Retentivity	, any torny minico by the main memory
— adjustable	Yes
— adjustable Data areas and their retentivity	160
	410 khyto: For storage in NVDAM: for storage in mass storage 5.040,000 bytes
Retentive data area (incl. timers, counters, flags), max.	410 kbyte; For storage in NVRAM; for storage in mass storage 5 242 020 bytes
Flag	16 khyto
Size, max. Number of cleek memories.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte

Data blocks	
Retentivity adjustable	Yes
Retentivity preset	No
Local data	
per priority class, max.	64 kbyte; max. 16 KB per block
Address area	
Number of IO modules	8 192
I/O address area	
• Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All outputs are in the process image
Subprocess images	
 Number of subprocess images, max. 	32
Hardware configuration	
Integrated power supply	Yes
Number of distributed IO systems	20
Number of DP masters	
• Via CM	1
Number of IO Controllers	
via PC interfaces	1
Rack	
Modules per rack, max.	64; CPU 1515SP PC + 64 modules + server module
Number of lines, max.	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available
Transcrott a civio	slots
Time of day	
Clock	
• Type	Hardware clock
Hardware clock (real-time)	Yes; Resolution: 1 s
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Clock synchronization	
• supported	Yes
• to DP, master	Yes
on Ethernet via NTP	Yes
on Windows clock, device	Yes
Interfaces	130
Number of industrial Ethernet interfaces	2
Number of PROFINET interfaces	1
Number of PROFIBUS interfaces	1; Via CM DP module
Number of RS 485 interfaces	1; Via CM DP module
Number of USB interfaces	4; 2x USB 2.0, 2x USB 3.0 on front side
Number of SD card slots	1
Video interfaces	
Graphics interface	1x DisplayPort
1. Interface	
Interface type	PROFINET
automatic detection of transmission rate	Yes
Autonegotiation	Yes
Autocrossing	Yes
Number of connections	88
Interface types	
• RJ 45 (Ethernet)	Yes; Via BusAdapter BA 2x RJ45
 Transmission rate, max. 	100 Mbit/s
 Industrial Ethernet status LED 	Yes
 Number of ports 	2
integrated switch	Yes
BusAdapter (PROFINET)	Yes; Compatible BusAdapter: BA 2x RJ45, BA 2x FC, BA 2x SCRJ (from FS03, V2.2), BA SCRJ / RJ45 (from FS03, V3.1), BA SCRJ / FC (from FS03, V3.1), BA 2x LC (from FS03, V3.3), BA LC / RJ45 (from FS03, V3.3), BA LC / FC
	(from FS03, V3.3)
Protocols	

PROFINET IO Controller	Yes
PROFINET IO Device	Yes
 SIMATIC communication 	Yes
Open IE communication	Yes
Web server	Yes
PROFINET IO Controller	
Services	
— Isochronous mode	Yes
 shortest clock pulse 	500 μs
— IRT	Yes
— PROFlenergy	Yes
— Prioritized startup	Yes; max. 32 PROFINET devices; if you want to use the "Prioritized startup" functionality in STEP 7 for the PROFINET interface of the CPU, the CPU and the device must be separated by means of a switch (e.g. SCALANCE X205)
 Number of connectable IO Devices, max. 	128
 Of which IO devices with IRT, max. 	64
— of which in line, max.	64
 Number of connectable IO Devices for RT, max. 	128
— of which in line, max.	128
 Number of IO Devices that can be simultaneously activated/deactivated, max. 	8
— IO Devices changing during operation (partner ports), supported	Yes
Number of IO Devices per tool, max.	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of
	configured user data
Update time for IRT	
— for send cycle of 500 μs	500 μs to 8 ms
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
 With IRT and parameterization of "odd" send cycles 	Update time = set "odd" send clock (any multiple of 125 μ s: 375 μ s, 625 μ s 3 875 μ s)
Update time for RT	
— for send cycle of 500 μs	500 μs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
Address area	
— Inputs, max.	8 kbyte
— Outputs, max.	8 kbyte
PROFINET IO Device	
Services	
— Isochronous mode	No
— shortest clock pulse	500 µs
— IRT	Yes
— PROFlenergy	Yes
 Prioritized startup 	Yes
— Shared device	Yes
 Number of IO Controllers with shared device, max. 	4
Asset management record	Yes
2. Interface	
Interface type	Integrated Ethernet interface
automatic detection of transmission rate	Yes
Autonegotiation	Yes
Autocrossing	Yes
Interface types	
• RJ 45 (Ethernet)	Yes; Integrated
— Transmission rate, max.	1 000 Mbit/s
Industrial Ethernet status LED	No
Number of ports	1
3. Interface	

Interface type	PROFIBUS with CM DP
Interface type Number of connections	PROFIBUS WITH CM DP
Interface types	44
• RS 485	Yes
Protocols	Tes
PROFIBUS DP master	Yes
PROFIBUS DP device	Yes
SIMATIC communication	Yes
PROFIBUS DP master	166
max. number of DP devices	125
Services	
— Equidistance	No
Isochronous mode	No
Address area	
— Inputs, max.	8 kbyte
— Outputs, max.	8 kbyte
Interface types	
RS 485	
Transmission rate, max.	12 Mbit/s
Protocols	
PROFIsafe	Yes
Number of connections	
Number of connections, max.	88
 Number of connections reserved for ES/HMI/web 	10
Number of S7 routing paths	16
Redundancy mode	
Media redundancy	
— MRP	Yes
— MRPD	Yes
 Switchover time on line break, typ. 	200 ms
 Number of stations in the ring, max. 	50
SIMATIC communication	
 PG/OP communication 	Yes
• S7 routing	Yes
 S7 communication, as server 	Yes
 S7 communication, as client 	Yes
User data per job, max.	64 kbyte; BSEND/BRCV: 64 KB; PUT/GET: 960 bytes
Open IE communication	
• TCP/IP	Yes
— Data length, max.	64 kbyte
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	1 472 kbyte
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
Web server	Van No Modern and DDOCHIET's 1
• HTTP	Yes; Via Windows and PROFINET interface
• HTTPS	Yes; Via Windows and PROFINET interface
OPC UA • Puntime license required	Vac: "Small" license required
 Runtime license required OPC UA Client 	Yes: "Small" license required
OPC UA Client OPC UA Server	Yes; From SW CPU 1505SP V2.6
Application authentication	Yes; Data access (read, write, subscribe), runtime license required Yes; Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— Security policies	Yes; Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— User authentication	Yes; "anonymous" or by user name & password
Further protocols	
• MODBUS	Yes; MODBUS TCP

S7 message functions	
Number of login stations for message functions, max.	32
Program alarms	Yes
Number of configurable program messages, max.	10 000
Number of simultaneously active program alarms	1 000
 Number of program alarms 	1 000
 Number of alarms for system diagnostics 	200
Number of alarms for motion technology objects	160
Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 8 engineering systems
Status block	Yes; up to 8 simultaneously
Single step	No
Number of breakpoints	8
Status/control	
Status/control variable	Yes
 Variables 	Inputs, outputs, memory bits, DB, times, counters
 Number of variables, max. 	
— of which status variables, max.	200
of which control variables, max.	200
Forcing	
• Forcing	Yes
• Forcing, variables	Inputs, outputs
Number of variables, max.	200
Diagnostic buffer	
• present	Yes
·	1 000
Number of entries, max.	300
— of which powerfail-proof	300
Traces	4
Number of configurable Traces	4
Memory size per trace, max.	512 kbyte
Interrupts/diagnostics/status information	
Diagnostics indication LED	
Diagnostics indication LED • RUN/STOP LED	Yes
Diagnostics indication LED	Yes Yes
Diagnostics indication LED • RUN/STOP LED	
Diagnostics indication LED • RUN/STOP LED • ERROR LED	Yes
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED	Yes
Diagnostics indication LED • RUN/STOP LED • ERROR LED • MAINT LED Supported technology objects	Yes Yes
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for	Yes Yes
Diagnostics indication LED • RUN/STOP LED • ERROR LED • MAINT LED Supported technology objects Motion Control • Number of available Motion Control resources for technology objects	Yes Yes
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources	Yes Yes 2 400
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis	Yes Yes 2 400 40; per axis
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis	Yes Yes Yes 2 400 40; per axis 80; per axis
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis	Yes Yes Yes 2 400 40; per axis 80; per axis 160; per axis
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder	Yes Yes Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track	Yes Yes Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe	Yes Yes Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle	Yes Yes Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle	Yes Yes Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value)	Yes Yes Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller	Yes Yes Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe 15 30
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact	Yes Yes Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe 15 30 Yes; Universal PID controller with integrated optimization
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_SStep	Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe 15 30 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Compact PID_Temp	Yes Yes Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe 15 30 Yes; Universal PID controller with integrated optimization
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring	Yes Yes Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe 15 30 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring High-speed counter	Yes Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe 15 30 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring High-speed counter Standards, approvals, certificates	Yes Yes Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe 15 30 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring High-speed counter	Yes Yes Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe 15 30 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature

SIL acc. to IEC 61508 Probability of failure (for convice life of 20 years and repair time)	SIL 3
Probability of failure (for service life of 20 years and repair time	·
— Low demand mode: PFDavg in accordance with SIL3	< 2.00E-05
 High demand/continuous mode: PFH in accordance with SIL3 	< 1.00E-09 1/h
pient conditions	
nbient temperature during operation	
• min.	-40 °C; = Tmin
• max.	Up to 60 $^{\circ}\text{C}$ with max. 32 ET 200SP modules; up to 55 $^{\circ}\text{C}$ with max. 64 ET 200SP modules
• horizontal installation, min.	-40 °C; = Tmin (incl. condensation/frost)
 horizontal installation, max. 	60 °C; = Tmax
 vertical installation, min. 	-40 °C; = Tmin
 vertical installation, max. 	50 °C; = Tmax; with max. 32 ET 200SP modules
nbient temperature during storage/transportation	
• min.	-40 °C
• max.	70 °C
itude during operation relating to sea level	
	2 000 m
Installation altitude above sea level, max. Ambient sir temperature become trie pressure altitude.	2 000 m
Ambient air temperature-barometric pressure-altitude	Tmin Tmax at 1 140 hPa 795 hPa (-1 000 m +2 000 m)
elative humidity	
 With condensation, tested in accordance with IEC 60068- 2-38, max. 	100 %; RH incl. condensation / frost (no commissioning in bedewed state), horizontal installation
brations	
 Operation, tested according to IEC 60068-2-6 	Yes
Transport, tested acc. to IEC 60068-2-6	Yes
nock testing	
 tested according to IEC 60068-2-6 	Yes
• tested according to IEC 60068-2-27	Yes
• tested according to IEC 60068-2-29	Yes
 Storage/transport, tested acc. to IEC 60068-2-27 	Yes
esistance	
Coolants and lubricants	
Resistant to commercially available coolants and lubricants	Yes; Incl. diesel and oil droplets in the air
Use in stationary industrial systems	
— to biologically active substances according to EN 60721-3-3	Yes; Class 3B2 mold, fungus and dry rot spores (with the exception of fauna) Class 3B3 on request
 to chemically active substances according to EN 60721-3-3 	Yes; Class 3C4 (RH < 75 %) incl. salt spray acc. to EN 60068-2-52 (severity degree 3); *
 to mechanically active substances according to EN 60721-3-3 	Yes; Class 3S4 incl. sand, dust, *
 Against mechanical environmental conditions acc. to EN 60721-3-3 	Yes; Class 3M8 using the SIPLUS Mounting Kit ET 200SP (6AG1193-6AA00 0AA0)
Use on ships/at sea	
— to biologically active substances according to EN 60721-3-6	Yes; Class 6B2 mold, fungal and dry rot spores (excluding fauna)
 to chemically active substances according to EN 60721-3-6 	Yes; Class 6C3 (RH < 75 %) incl. salt spray acc. to EN 60068-2-52 (severity degree 3); *
 to mechanically active substances according to EN 60721-3-6 	Yes; Class 6S3 incl. sand, dust; *
 Against mechanical environmental conditions acc. to EN 60721-3-6 	Yes; Class 6M4 using the SIPLUS Mounting Kit ET 200SP (6AG1193-6AA00 0AA0)
Usage in industrial process technology	
 Against chemically active substances acc. to EN 60654-4 	Yes; Class 3 (excluding trichlorethylene)
 Environmental conditions for process, measuring and control systems acc. to ANSI/ISA-71.04 	Yes; Level GX group A/B (excluding trichlorethylene; harmful gas concentrations up to the limits of EN 60721-3-3 class 3C4 permissible); level LC3 (salt spray) and level LB3 (oil)
Remark	
 Note regarding classification of environmental conditions acc. to EN 60721, EN 60654-4 and ANSI/ISA-71.04 	* The supplied plug covers must remain in place over the unused interfaces during operation!
onformal coating	
ornormal coaling	

61086

• Protection against fouling acc. to EN 60664-3

• Military testing according to MIL-I-46058C, Amendment 7

 Qualification and Performance of Electrical Insulating Compound for Printed Board Assemblies according to IPC-CC-830A Yes; Type 1 protection

Yes; Discoloration of coating possible during service life

Yes; Conformal coating, Class A

Operating systems	
pre-installed operating system	Windows 10 IoT Enterprise 2016 LTSB, 64bit, MUI
configuration / header	
configuration / programming / header	
Programming language	
— LAD	Yes; incl. failsafe
— FBD	Yes; incl. failsafe
— STL	Yes
— SCL	Yes
— CFC	No
— GRAPH	Yes
Know-how protection	
 User program protection/password protection 	Yes
 Copy protection 	Yes
Block protection	Yes
Access protection	
 Protection level: Write protection 	Yes
 Protection level: Read/write protection 	Yes
Protection level: Complete protection	Yes
programming / cycle time monitoring / header	
 lower limit 	adjustable minimum cycle time
upper limit	adjustable maximum cycle time
Open Development interfaces	
 Size of ODK SO file, max. 	5.8 Mbyte
Peripherals/Options	
SD card	Optionally for additional mass storage
Dimensions	
Width	160 mm
Height	117 mm
Depth	75 mm
Weights	
Weight, approx.	0.83 kg

last modified:

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